

**Computational and Applied Mathematics**

1. Let  $A \in \mathbb{R}^{n \times n}$  be a non-singular matrix. Let  $u, v \in \mathbb{R}^n$  be column vectors. Define the rank 1 perturbation  $\hat{A} = A + uv^T$ .

- (a) Derive a necessary and sufficient condition for  $\hat{A}$  to be invertible.
- (b) Let  $x, z$  and  $b$  be column vectors in  $\mathbb{R}^n$ . Suppose one can solve  $Az = b$  with  $\mathcal{O}(n)$  floating-point operations (flops). Under the conditions derived in (a), design an algorithm to solve  $\hat{A}x = b$  with  $\mathcal{O}(n)$  flops, and provide justification for your answer.

2. Consider the integral

$$\int_0^\infty f(x) dx$$

where  $f$  is continuous,  $f'(0) \neq 0$ , and  $f(x)$  decays like  $x^{-1-\alpha}$  with  $\alpha > 0$  in the limit  $x \rightarrow \infty$ .

- (a) Suppose you apply the equispaced composite trapezoid rule with  $n$  subintervals to approximate

$$\int_0^L f(x) dx.$$

What is the asymptotic error formula for the error in the limit  $n \rightarrow \infty$  with  $L$  fixed?

- (b) Suppose you consider the quadrature from (a) to be an approximation to the full integral from 0 to  $\infty$ . How should  $L$  increase with  $n$  to optimize the asymptotic rate of total error decay? What is the rate of error decrease with this choice of  $L$ ? 5

- (c) Make the following change of variable  $x = \frac{L(1+y)}{1-y}$ ,  $y = \frac{x-L}{x+L}$  in the original integral to obtain

$$\int_{-1}^1 F_L(y) dy.$$

Suppose you apply the equispaced composite trapezoid rule; what is the asymptotic error formula for fixed  $L$ ?

- (d) Depending on  $\alpha$ , which method - domain truncation or change-of-variable - is preferable?

3. Consider the Chebyshev polynomial of the first kind

$$T_n(x) = \cos(n\theta), \quad x = \cos(\theta), \quad x \in [-1, 1].$$

The Chebyshev polynomials of the second kind are defined as

$$U_n(x) = \frac{1}{n+1} T'_n(x), \quad n \geq 0.$$

- (a) Derive a recursive formula for computing  $U_n(x)$  for all  $n \geq 0$ .
- (b) Show that the Chebyshev polynomials of the second kind are orthogonal with respect to the inner product

$$\langle f, g \rangle = \int_{-1}^1 f(x)g(x)\sqrt{1-x^2} dx$$

- (c) Derive the 2-point Gaussian Quadrature rule for the integral

$$\int_{-1}^1 f(x)\sqrt{1-x^2} dx = \sum_{j=1}^2 w_j f(x_j)$$

4. Consider the boundary value problem

$$-\frac{d}{dx} \left( a(x) \frac{du}{dx} \right) = f(x), \quad u(0) = u(1) = 0$$

where  $a(x) > \delta \geq 0$  is a bounded differentiable function in  $[0, 1]$ . We assume that, although  $a(x)$  is available, an expression for its derivative,  $\frac{da}{dx}$ , is not available.

- (a) Using finite differences and an equally spaced grid in  $[0, 1]$ ,  $x_l = hl, l = 0, \dots, n$  and  $h = 1/n$ , we discretize the ODE to obtain a linear system of equations, yielding an  $O(h^2)$  approximation of the ODE. After the application of the boundary conditions, the resulting coefficient matrix of the linear system is an  $(n-1) \times (n-1)$  tridiagonal matrix.

Provide a derivation and write down the resulting linear system (by giving the expressions of the elements).

- (b) Utilizing all the information provided, find a disc in  $\mathbb{C}$ , the smaller the better, that is guaranteed to contain all the eigenvalues of the linear system constructed in part (a).

5. (a) Verify that the PDE

$$u_t = u_{xxx}$$

is well posed as an initial value problem.

- (b) Consider solving it numerically using the scheme

$$\frac{u(t+k, x) - u(t-k, x)}{2k} = \frac{-\frac{1}{2}u(x-2h, t) + u(x-h, t) - u(x+h, t) + \frac{1}{2}u(x+2h, t)}{h}.$$

Determine this scheme's stability condition.

6. Consider the diffusion equation

$$\frac{\partial v}{\partial t} = \mu \frac{\partial^2 v}{\partial x^2}, \quad v(x, 0) = \phi(x), \quad \int_a^b v(x, t) dx = 0$$

with  $x \in [a, b]$  and periodic boundary conditions. The solution is to be approximated using the central difference operator  $L$  for the 1D Laplacian.

$$Lv_m = \frac{v_{m+1} - 2v_m + v_{m-1}}{h^2},$$

and the following two finite different approximations, (i) Forward-Euler

$$v_{n+1} = v_n + \mu k Lv_n, \tag{1}$$

and (ii) Crank-Nicolson

$$v_{n+1} = v_n + \mu k (Lv_n + Lv_{n+1}). \tag{2}$$

Throughout, consider  $[a, b] = [0, 2\pi]$  and the finite difference stencil to have periodic boundary conditions on the spatial lattice  $[0, h, 2h, \dots, (N-1)h]$  where  $h = \frac{2\pi}{N}$  and  $N$  is even.

- (a) Determine the order of accuracy of the central difference operator  $Lv$  in approximating the second derivative  $v_{xx}$ .
- (b) Using  $v_m^n = \sum_{l=0}^{N-1} \hat{v}_l^n \exp\left(-i\frac{2\pi lm}{N}\right)$  give the updates  $\hat{v}_l^{n+1}$  in terms of  $\hat{v}_l^n$  for each of the methods, including the case  $l = 0$ .
- (c) Give the solution for  $v_m^n$  for each method when the initial condition is  $\phi(m\Delta x) = (-1)^m$ .
- (d) What are the stability constraints on the time step  $k$  for each of the methods, if any, in equations (1) and (2)? Show there are either no constraints or express them in the form  $k \leq F(h, \mu)$ .